The Connected Car: Will Autonomous Vehicles Finally Get Them on the Road?

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Announcing: the 2021 connected car!

Engineers push state of the art...secure, high bandwidth, no interference!



First some terms...

Every technology has its acronyms!

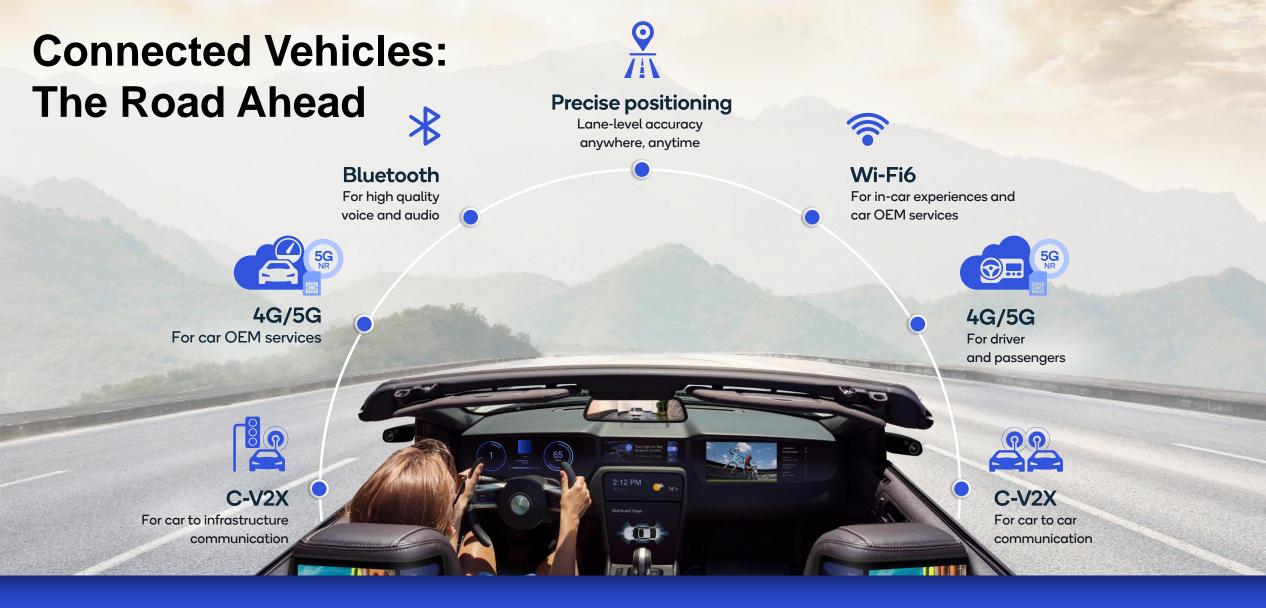
- AV: Automated Vehicles
- CAV: Connected and Automated Vehicles
- ADAS: Advanced Driver Assistance Systems Sensors and control systems that sense, warn, and possibly control (brake, steer) a vehicle
- V2X: Vehicle to anything communication (vehicles, infrastructure, pedestrians, networks, etc.)
- DSRC: Dedicated Short Range Communication A communications protocol/stack based on 802.11p radio access technology, with the ability to do V2X communication in the 5.9GHz band
- Cellular-V2X: A communications protocol/stack based on 3GPP Release-14 PC5 Sidelink radio access technology, with the ability to do V2X communication in the 5.9GHz band (aka LTE-V2X)
- 5G NR: 3GPP "New Radio" Release-16 (and beyond) enhanced capabilities for AV
- SAE: Society of Automotive Engineers develops specifications for automated driving levels (J3016), V2X message types (J2735), upper layer protocols/standards/test procedures for DSRC and C-V2X (J2945 & J3161 families)

The big picture....

V2X – whether for ADAS or AV – is addressing big issues in transportation

Safety

- Traffic deaths 34,247 in the US in 2017 (NHTSA)
 - <u>https://cdan.nhtsa.gov/tsftables/National%20Statistics.pdf</u>
 - Large percentage is due to human error
- \circ Injuries 1,889000 in the US in 2017 (NHTSA)
- Property damage 4,530,000 crashes
- In addition:
 - 3.1B gallons of fuel wasted due to traffic congestion
 - 14% of all global warming emissions from transportation
 - Countless hours of time wasted
- Modern safety assistance and Automated Vehicles are expected to reduce fatalities and injury
 - Sensors will be in (almost) all vehicles
 - Increasing numbers of vehicles will be connected, either direct V2V or through WAN (V2N or V2N2V)



Car connectivity in the 5G era

Heterogeneous connectivity Secure, virtualized wireless links

Advanced positioning

Multi-environment implementation

V2X History

FCC allocated 70MHz for DSRC in 1999 (5850-5925MHz)

Originally Based on 802.11a (and 802.11j)

Uses 10 MHz channel option defined similar to 802.11j (1/2 clocked from 20 MHz)

Tighter spectral mask

Slightly different MAC (OCB plus 1609.x

enhancements)

Differences in layers above PHY and MAC as well

Special FCC channel designations:

Ch. 172 is for vehicle collision avoidance communication

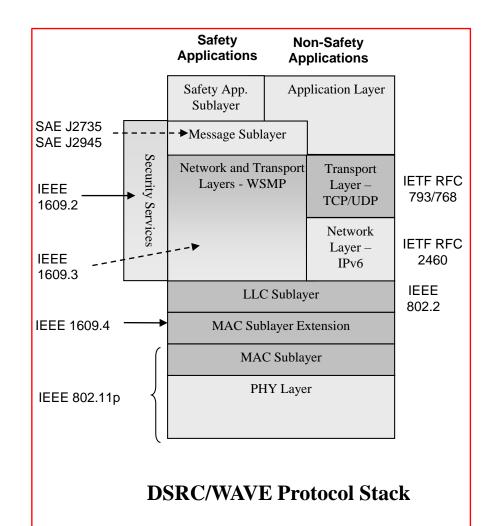
Basic Safety Message (BSM) sent using 3Mbps preamble (R=1/2, BPSK), 6Mbps payload (R=1/2, QPSK)

Ch.178 is the control channel

Ch. 184 is for long distance public safety communication

Europe: Similar band/channelization

Japan: Uses 11p PHY in 760 MHz, but higher layers quite different.



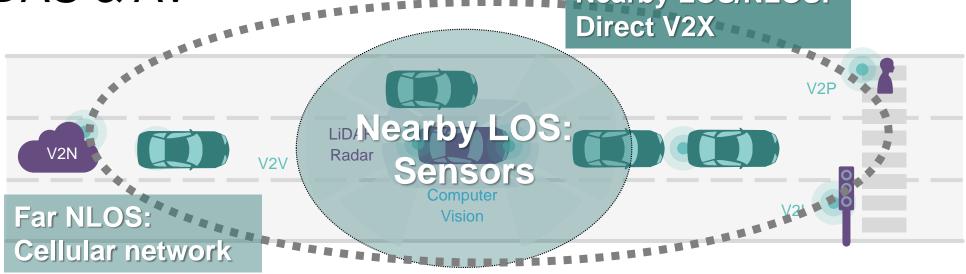
Changes in Automotive and Communication Technology

Rapid evolution in sensor and cellular technology have changed the connected vehicle landscape

- In the 20 years since the ITS spectrum was allocated, vehicles have significantly increased ADAS capabilities
 - Sensors radar, cameras, ultrasound/sonar, lidar
 - Processing artificial intelligence
- 802.11p (based on 802.11a) is a relatively old communication technology
 - Cellular technology has advanced dramatically over the last 20 years
 - Robustness and reliability have significantly improved especially NLOS
 - 3GPP added the capability for device to device...allows vehicles to communicate without infrastructure: Cellular-V2X
- The FCC changed the spectrum allocation in December 2020 to reflect these changes and made C-V2X the de facto standard

Sensors + AI + advanced wireless technology = improved safety

V2X is a key technology enabler for enhanced ADAS & AV Nearby LOS/NLOS:



- Sensors: Camera, Radar. Lidar, ultrasonic, etc. typically Line of Sight (LOS)
- Direct V2X: DSRC/C-V2X augments sensors with additional information, especially Non-Line of Sight (NLOS)
 - BSM time critical situational awareness of vehicles around you
 - I2V/V2I SPaT, MAP, TIM, etc
- WAN (V2N and V2N2V)
 - Now Non-time critical, wider area information about traffic, weather, etc.
 - 5G URLLC...relay information between vehicles in a few milliseconds
- Processing
 - Al/compute power fuses information together for ADAS and/or AV

SAE Automated Driving Levels



SAE J3016[™] LEVELS OF DRIVING AUTOMATION

Connected and Automated Vehicles:

Automated vehicles are usually assumed to be connected, but a connected vehicle may not be automated

SÆ SÆ S4E S4E SÆ SÆ **LEVEL 4** LEVEL O LEVEL 2 LEVEL 1 LEVEL 3 LEVEL 5 You are driving whenever these driver support features You are not driving when these automated driving are engaged - even if your feet are off the pedals and features are engaged - even if you are seated in What does the you are not steering "the driver's seat" human in the driver's seat When the feature You must constantly supervise these support features: These automated driving features have to do? you must steer, brake or accelerate as needed to will not require you to take maintain safety over driving you must drive

These are driver support features

These are automated driving features

What do these features do?	These features are limited to providing warnings and momentary assistance	These features provide steering OR brake/ acceleration support to the driver	These features provide steering AND brake/ acceleration support to the driver	These features can drive the vehicle under limited conditions and will not operate unless all required conditions are met		This feature can drive the vehicle under all conditions
Example Features	 automatic emergency braking blind spot warning lane departure warning 	 lane centering OR adaptive cruise control 	 lane centering AND adaptive cruise control at the same time 	•traffic jam chauffeur	 local driverless taxi pedals/ steering wheel may or may not be installed 	• same as level 4, but feature can drive everywhere in all conditions

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V2X Use Cases



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Connected urban transport



PC5-based C-V2X E.g. for collision avoidance and coordinated driving Precise positioning E.g. for lane management and lane-level navigation



Edge/on-device Al

E.g. for detecting hazards and speed harmonization

Reshaping our highways

Forward collision avoidance (via PC5-V2V) Teleoperation via 4G/5G networks

> TMC-based traffic monitoring and advisory (via 4G/5G networks)

> > 3D HD map update for automated driving (via I2V)

Automotive services Predictive maintenance Transportation efficiency Speed harmonization (via PC5 I2V)

Lane-based navigation (via precise positioning and 4G/5G networks)

Connected highways

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4G/5G networks E.g. for TMC-based traffic monitoring & advisory

Road safety Hazard warning (via PC5-V2I)

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PC5-based C-V2X E.g. for collision avoidance and coordinated driving



Precise positioning

E.g. for lane management and lane-level navigation

Bringing a comprehensive ecosystem together

Driving the future of smart transportation



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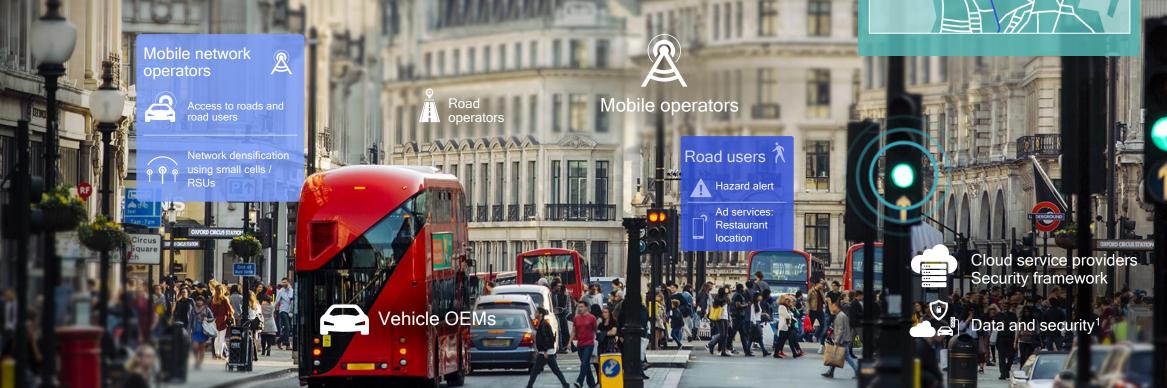
Available



Pay-as-you-use parking

236 Occupied \$472 Revenue per

Recommended toll routes



Facilitating multi-tiered services

1.11

Pedestrian detection AR-based navigation Virtual assistant

Traffic information



Feature management



Premium

ehicle features

SPEED LIMIT 65

Your music stations added

Day running City speed lights on limit set

On demand unlocking and locking

Context-based personalized information Premium



Cellular-V2X: What it is and how it works

What is Cellular-V2X?

Summary: It's a more modern radio doing direct V2X using the existing DSRC stacks

- C-V2X is based on 3GPP release 14 PC5 "Sidelink" (direct device to device)
 - It doesn't need a SIM, carrier access, or licensed spectrum
 - Doesn't require infrastructure but can communicate V2V or V2I
 - PC5 Modem can be integrated into telematics for cost savings
 - Radio access based on scheduled, deterministic reservations no CSMA/CA
 - PHY picks best (lowest energy) resources available for the reservation
 - Superior performance compared to 11p, especially in NLOS
 - Longer range/more robust at the same range
 - Fewer RSU's needed for coverage
- Layers above the PHY/MAC are almost identical to DSRC
 - Uses IEEE 1609.2 security
 - Uses SAE J2735 message set
 - Uses modified version of SAE J2945/1 (J3161) only changes in radio layer and congestion control

C-V2X reuses upper layers defined by ITS industry

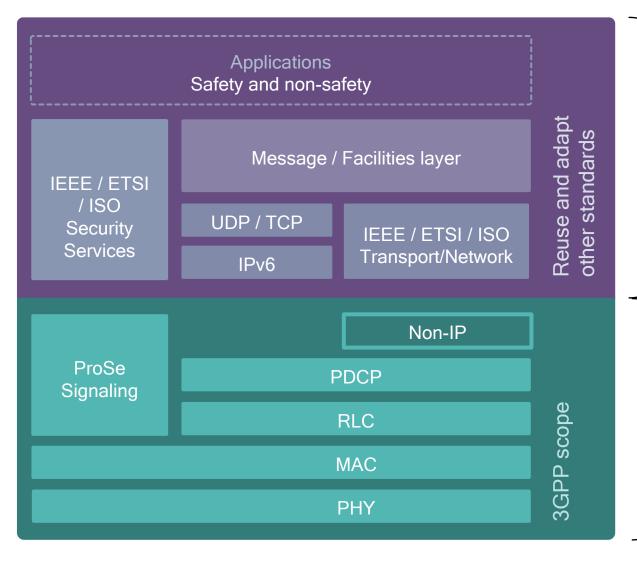
standards

Existing (

3GPP

Sidelink radio

PC5



Reuse established service and app layers

- Already defined by automotive and standards communities, e.g. ETSI, SAE
- Developing abstraction layer to interface with 3GPP lower layers (in conjunction with 5GAA)

Reuse existing security and transport layers

• Defined by ISO, ETSI, and IEEE 1609 family

Continuous enhancements to the radio/lower layers

• Supports the ever-evolving V2X use cases

V2V

Vehicle-to-vehicle e.g., collision avoidance safety systems

V2I

Vehicle-to-infrastructure e.g., traffic signal timing/priority

V2P

Vehicle-to-pedestrian e.g., safety alerts to pedestrians, bicyclists

V2N

Vehicle-to-network e.g., real-time traffic/routing, cloud services

Enhanced range and reliability for direct communication without network assistance



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C-V2X

Establishes the foundation for safety use cases and a continued 5G NR C-V2X evolution for future autonomous vehicles

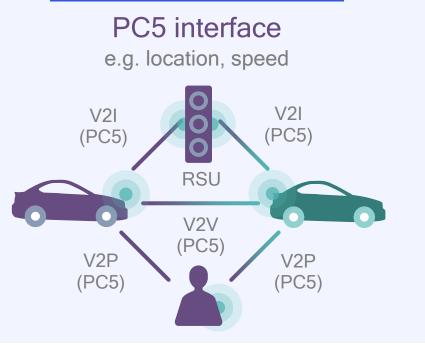
 Release 14 C-V2X completed in 2017
 5G Broad industry support – 5GAA
 Global trials started in 2017
 Our 1st announced C-V2X product in September, 2017

C-V2X defines two complementary transmission modes

Direct communications

V2V, V2I, and V2P on "PC5" Interface, operating in ITS bands (e.g. ITS 5.9 GHz) independent of cellular network

Similar to DSRC

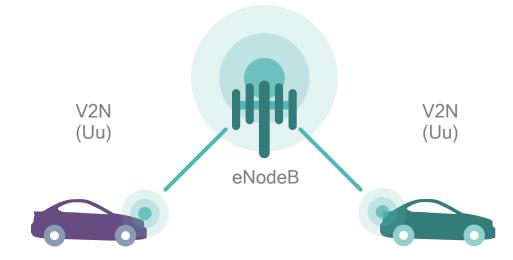


Network communications

V2N on "Uu" interface operates in traditional mobile broadband licensed spectrum

Uu interface

e.g. accident 2 kilometer ahead



C-V2X is designed to work without network assistance¹

V2V/V2I/V2P direct communications enables low latency applications

USIM-less operation

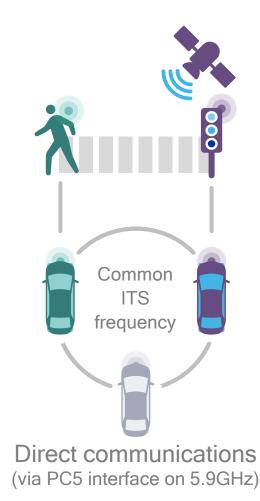
C-V2X direct communications doesn't require USIM

Autonomous resource selection

Distributed scheduling, where the car selects resources from resource pools without network assistance

GNSS time synchronization

Besides positioning², C-V2X also uses GNSS for time synchronization without relying on cellular networks



1; 3GPP also defines a mode, where eNodeB helps coordinate C-V2X Direct Communication; 2 GNSS is required for V2X technologies, including 802.11p, for positioning. Timing is calculated as part of the position calculations and it requires smaller number of satellites than those needed for positioning

C-V2X is designed to work in ITS 5.9 GHz spectrum

For vehicles to talk to each other on harmonized, dedicated spectrum

3GPP support of ITS 5.9 GHz band

C-V2X support in ITS band was added in 3GPP Release 14¹

Harmonized spectrum for safety

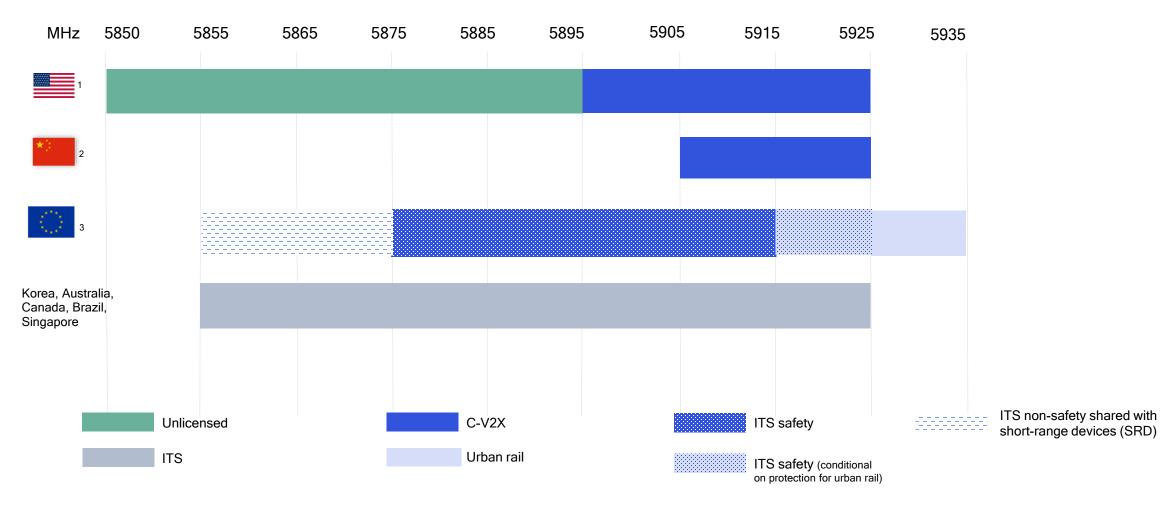
C-V2X uses harmonized/common, dedicated spectrum for vehicles to talk to each other communications

C-V2X direct

Coexistence with 802.11p (EU)

C-V2X and 802.11p can co-exist by being placed on different channels in the ITS band (in Europe)

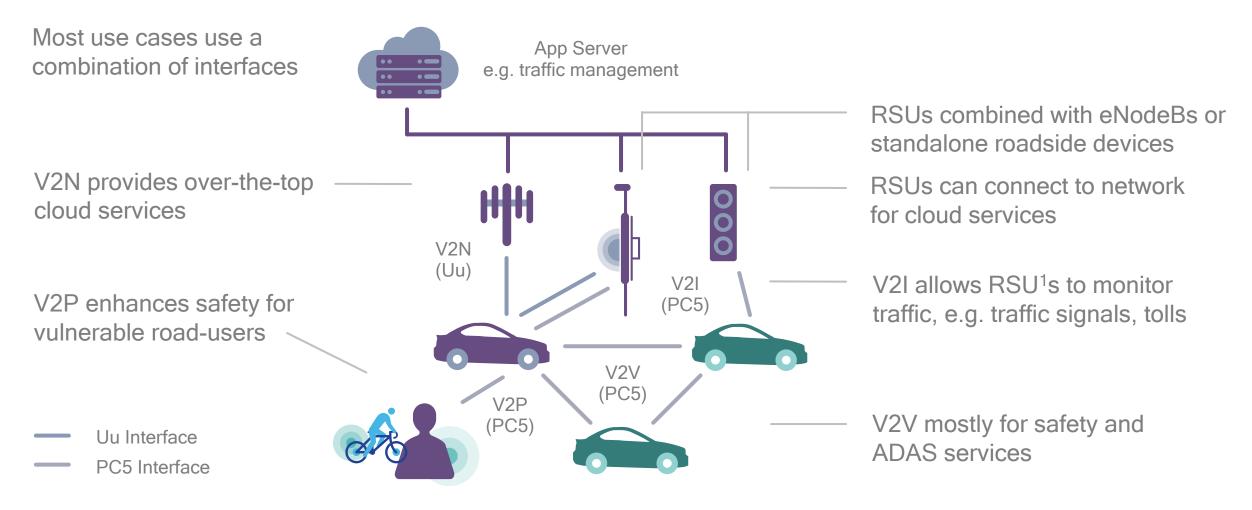
Global snapshot of allocated/targeted ITS spectrum



1 FCC assigned upper 30 MHz of ITS band (5.895-5.925 GHz, B47). 2 MIIT officially regulated the upper 20 MHz (5.905-5.925 GHz). 3 ITS spectrum allocation in Europe is still pending. The EU has adopted technology neutrality in spectrum allocation.

Advanced services further enabled by V2V+V2I+V2P+V2N

Offering new business models and enhancing most use cases



System is designed for high density vehicle deployments

Guaranteeing low latency access for safety critical messages even at high density



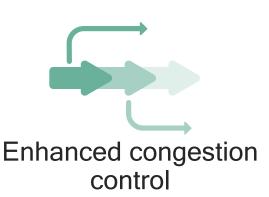
Deterministic resource scheduling

Choose resources with the lowest received energy leading to optimal resource selection



Guaranteed latency performance

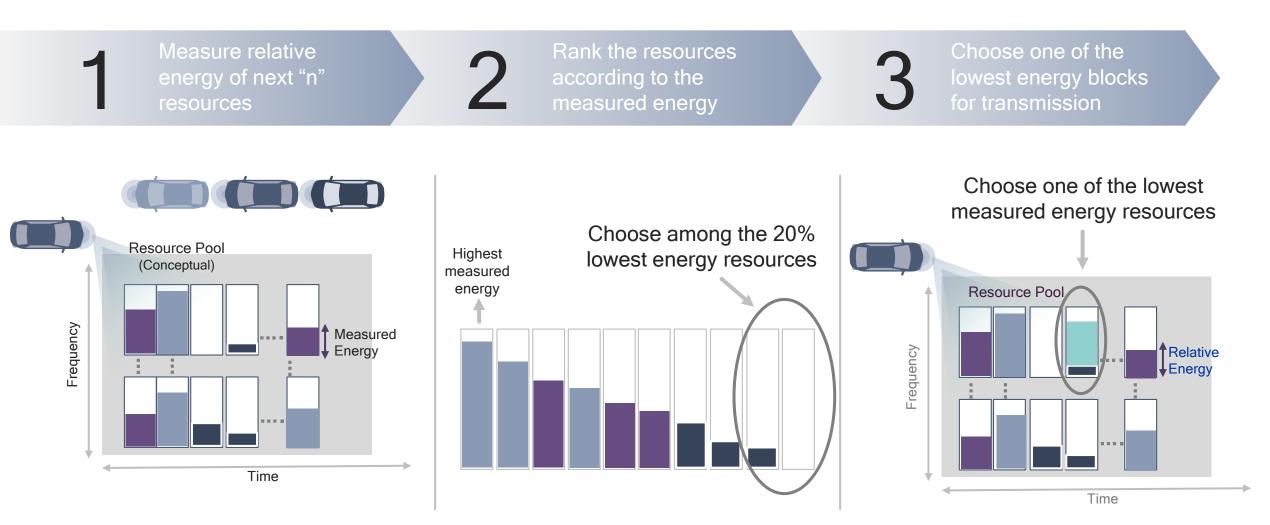
New methods using sensing and semipersistent resource selection that choose resource blocks with lowest energy levels to meet latency requirements

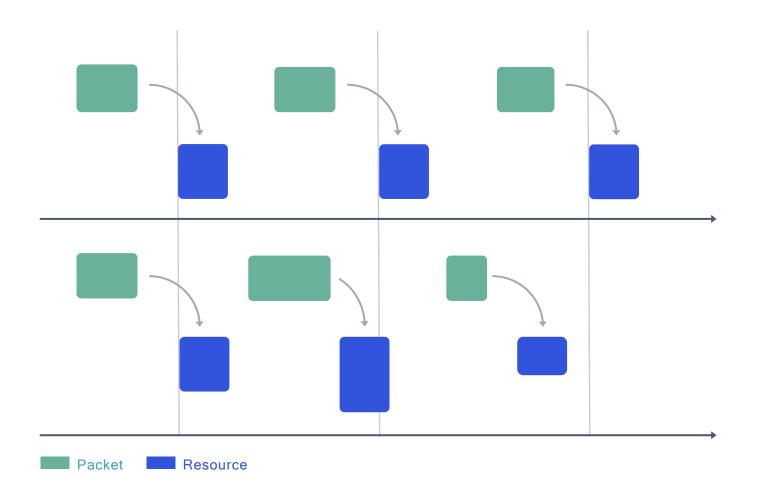


Enhanced performance with MAC/PHY congestion control with more flexible tools along with leveraging higher layers to tune congestion control parameters

Deterministic access control and resource scheduling

Chooses blocks with lowest energy levels, while meeting latency requirements





Semi-persistent scheduling

Suitable for basic safety messages with similar packet sizes

Periodic transmission (typically ~100 msec)

Per packet scheduling

Variable traffic model based on the varying packet sizes

Lower latency (< 100 msec)

Efficient and flexible resource allocation for advanced applications with variable traffic

Working with regional standards to define applications globally

SAE for North America, ETSI ITS for Europe, and C-SAE/C-ITS for China

Supporting emerging use cases



Standardizing messages for new use cases (e.g., sensor data sharing among vehicles)

Providing interoperability



Allowing vehicles from different automakers to benefit from new use cases

Specifying minimum requirements



Defining application layer-specific minimum requirements for new messages



Evolution

A world where virtually everyone and everything is intelligently connected

Scalable to extreme simplicit

Multi-gigabit speed

> Ultra-low latency

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Virtually unlimited

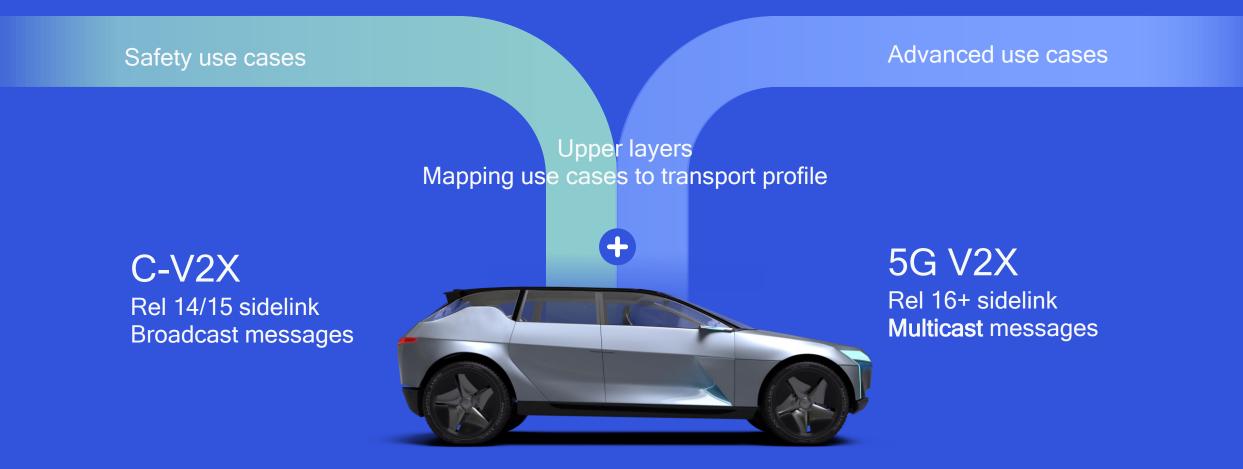
Extreme reliability

On-device



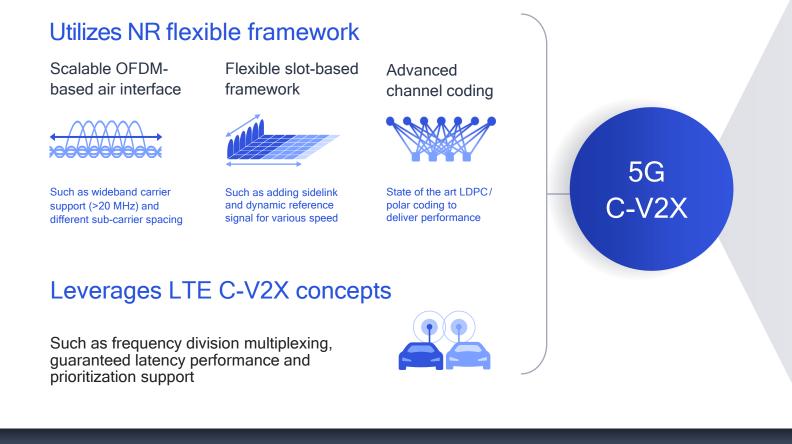
5G V2X builds on C-V2X

with advanced use cases



5G V2X sidelink

Building on existing frameworks



Introduces advanced capabilities

- Efficient sidelink link level design for optimized performance at all speeds
- Connectionless 'on-the-fly' distance-based groups
- Multicast with distance-based reliability and application relevancy

And increased performance

- Lower latency
- Higher spectral efficiency
- Higher capacity

NR C-V2X delivers a design that addresses advanced use cases

Significant physical layer gains

NR C-V2X enhancements

Spectral efficiency: up to 2x for broadcast

Scalable OFDM and flexible DMRS provide higher spectral efficiency, which reduces bandwidth usage and allow for more capacity

Lower latency: Tx latency as low as 1.5 ms

Due to shorter slots and resources allocation enhancements





Higher capacity: 2x for per packet scheduling

Achieved through link-level gain, HARQ feedback, and resource allocation enhancements



Should be notified, but does not get signal



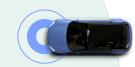
Uniform coverage by adding distance as a dimension



Location information shared efficiently in the physical layer control channel

Enables NAK feedback with HARQ based on distance





Groups can reliably connect based on distance



Vehicles within a certain distance and interested in same services form an 'on-the-fly' group

5G V2X enables advanced use cases



Increased situational awareness

Sharing of vehicle-specific info with other vehicles and road infrastructure (e.g. door open warning)



Sensor sharing

Sharing of sensor data, e.g., vehicle's perception, including road world model



Coordinated driving/ intention sharing

Exchanging intention and sensor data for more predictable, coordinated autonomous driving



Real-time infrastructure updates

Real-time sharing of 3D HD map and other information between vehicles and infrastructure

Higher throughput Lower latency

Higher reliability

Application aware

Conclusion

V2X is an emerging technology area (sort of)

- 5.9GHz spectrum has been available for 20 years
 - Very little deployment of 802.11p based DSRC so FCC has reallocated the lower 40MHz for unlicensed use and allocated the upper 30MHz (5895-5925MHz) exclusively for C-V2X
- 3GPP-based C-V2X is gaining traction
 - Uses "Sidelink" from Release 14 direct device to device communication
 - 5GAA over 120 member companies (<u>www.5gaa.org</u>)
 - \circ Ford has announced intention to deploy in model year 2022
- C-V2X will be complemented by 5G NR (Release 16+)
 - Advanced use cases (sensor sharing, HD maps, coordinated driving, platooning, see-through)
 - Enhancement specifically designed for Autonomous Vehicles
- 5G Uu (cellular) also complements C-V2X
 - Cooperative automated driving
 - \circ Teleoperation

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Backup

Designed to get synchronization from different sources







GNSS Satellite synchronization

GNSS can be the primary synchronization source

Infrastructure synchronization

3GPP has defined a detailed protocol for vehicles to use eNodeB/RSU as time synchronization source

UE synchronization

3GPP allows vehicles to use other vehicles on the road as a time synchronization source